

# ENPH 253 – Introduction to Instrument Design - Summer 2018

DRAFT Competition Rules – April 3, 2018

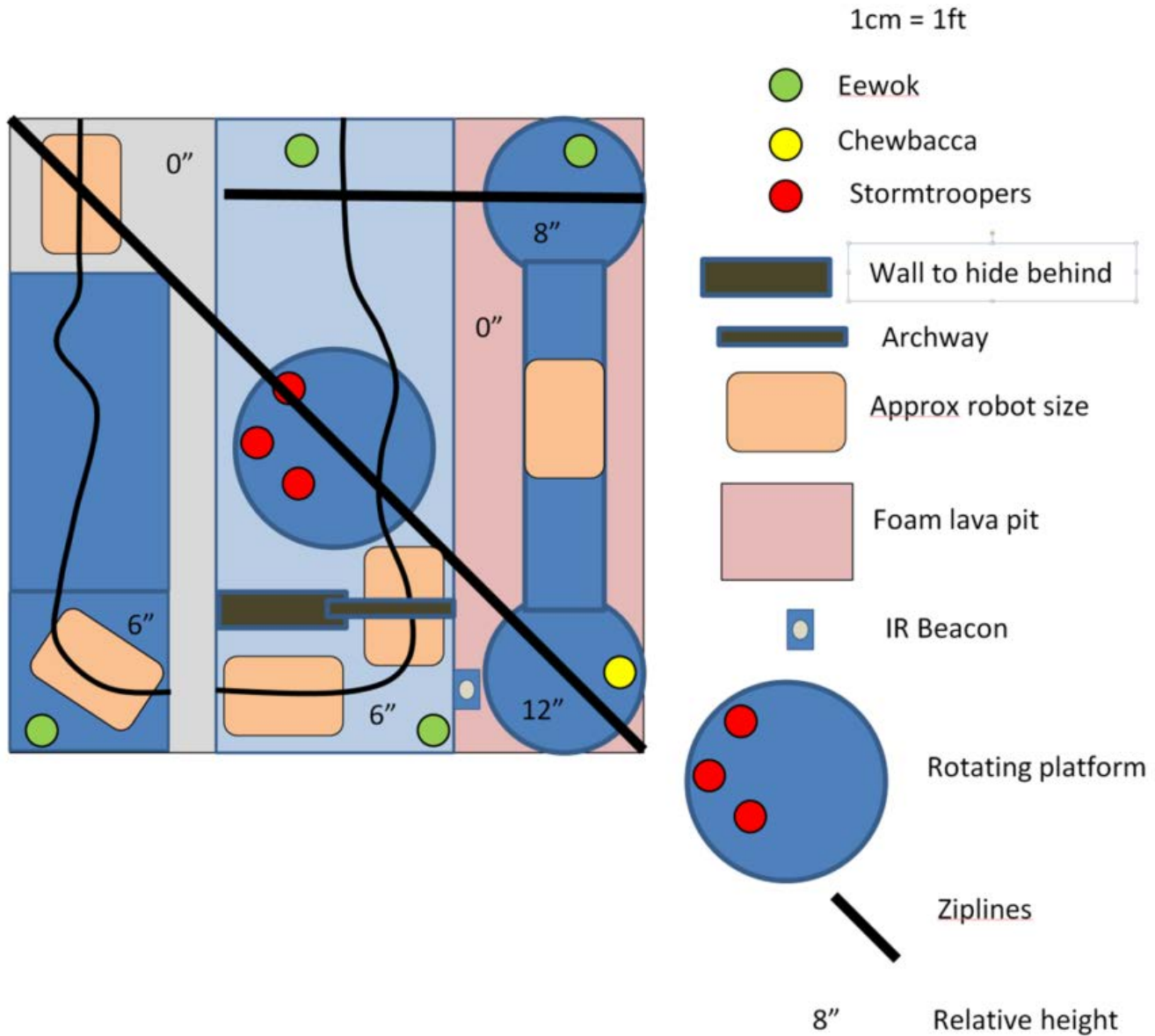
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## Ewok Rescue: A Star Warz Story



Chewbacca and the Ewoks have been trapped inside an Empire stronghold! When you last saw them they worshipped you as a God - now it's your turn to help them.

Figure 1 – Competition Surface



# “Smart” instruments

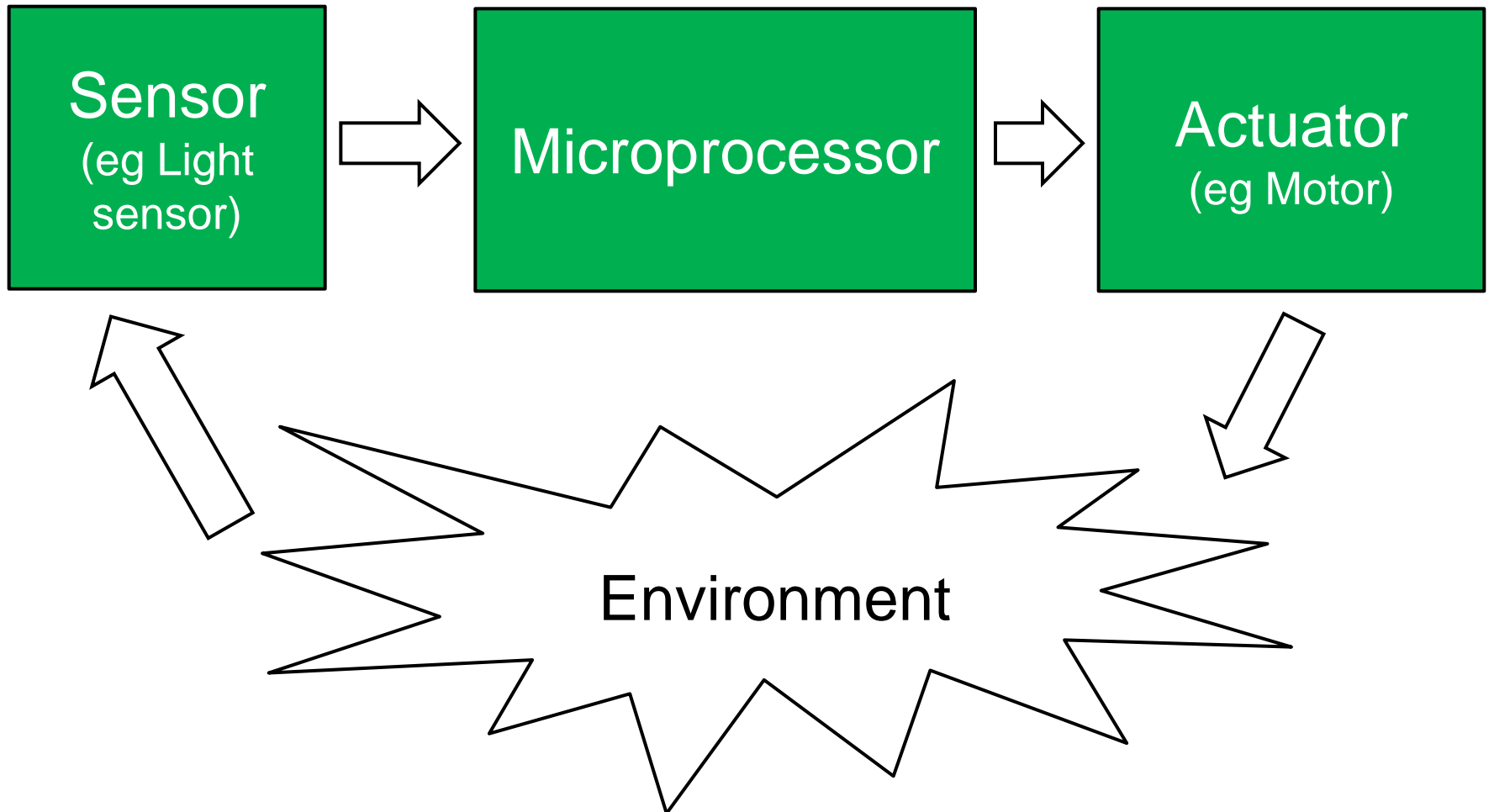
The use of microprocessors to replace mechanical systems leads to

- better performance
- higher reliability
- more complex behavior with a mechanically simpler instrument
- often lower total cost of instrument

Eg #1: mechanical vs. electronic thermostats



# “Smart” instruments



Rescue bot video

8 Analog inputs

6 PWM out

16 Digital Inputs

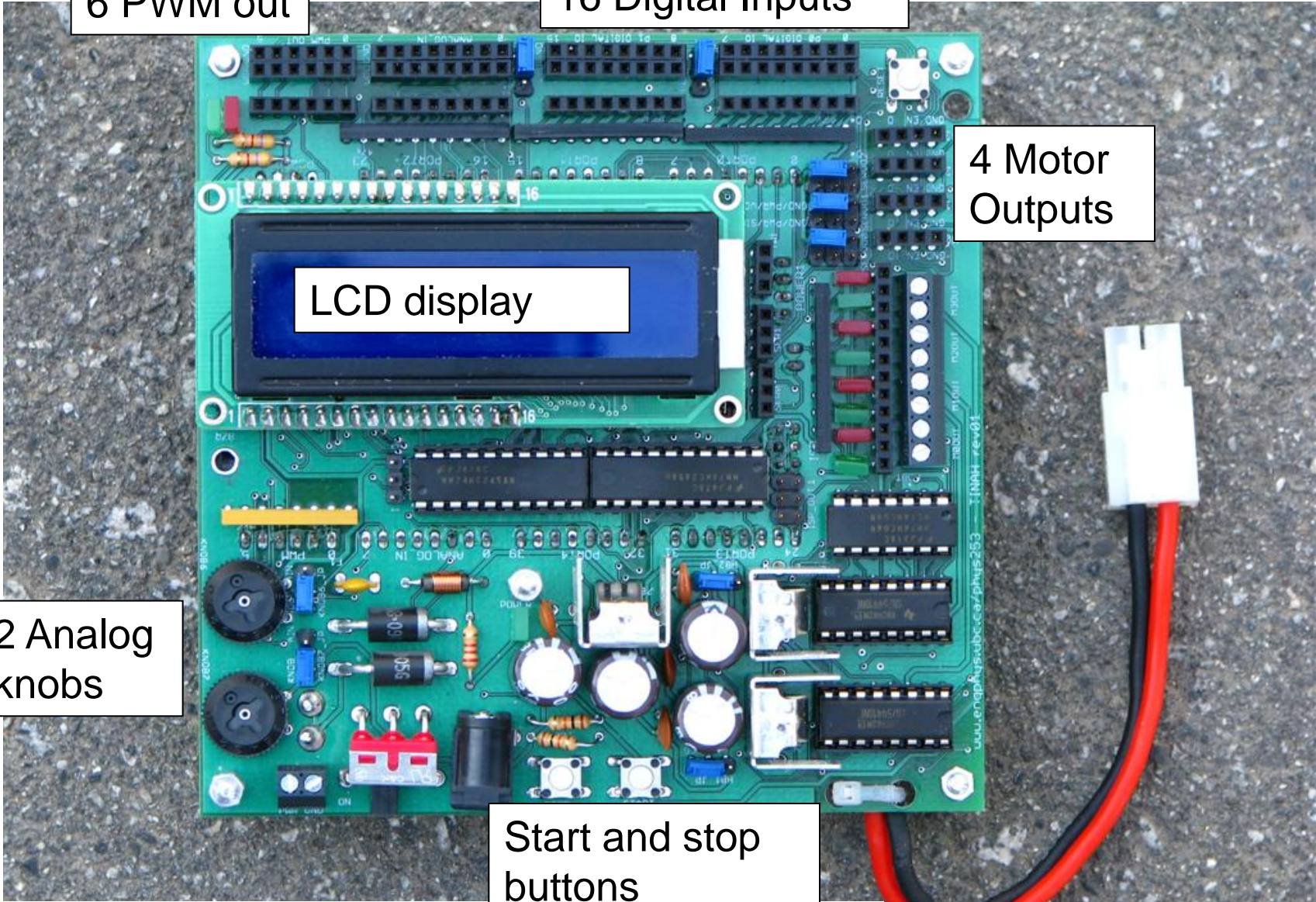
4 Motor Outputs

LCD display

2 Analog knobs

Start and stop buttons

TINAH microcontroller board

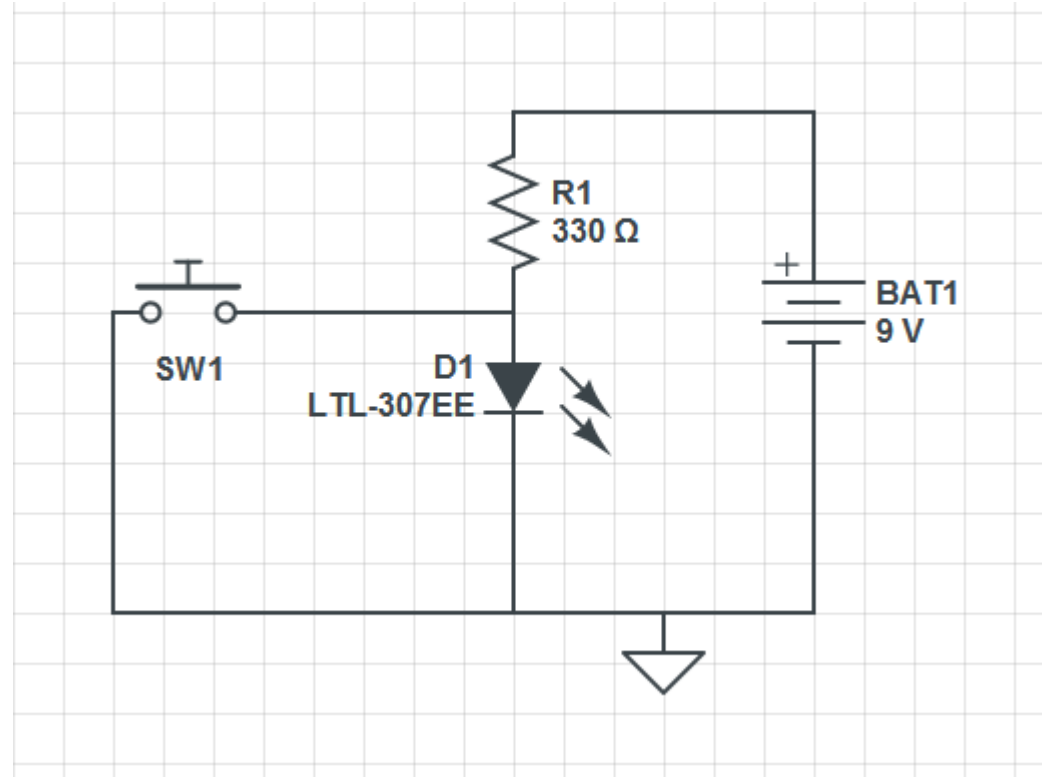


# **Step 1 – Getting your robot to detect its environment**

# Digital Inputs – Touch sensor

Build this circuit:

- LED is normally lit
- While the switch is pressed, the LED goes off



- Why do you need the 330R resistor?
- What happens if you remove it? (don't)



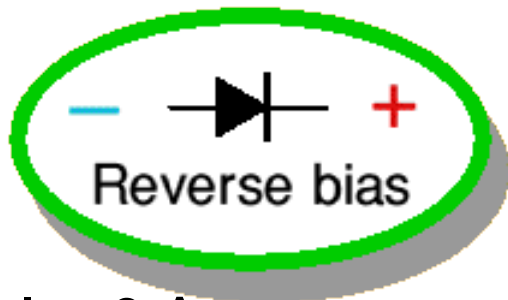
# Discrete devices: diodes



Forward bias

$$\Delta V = 0.7 \text{ V}$$

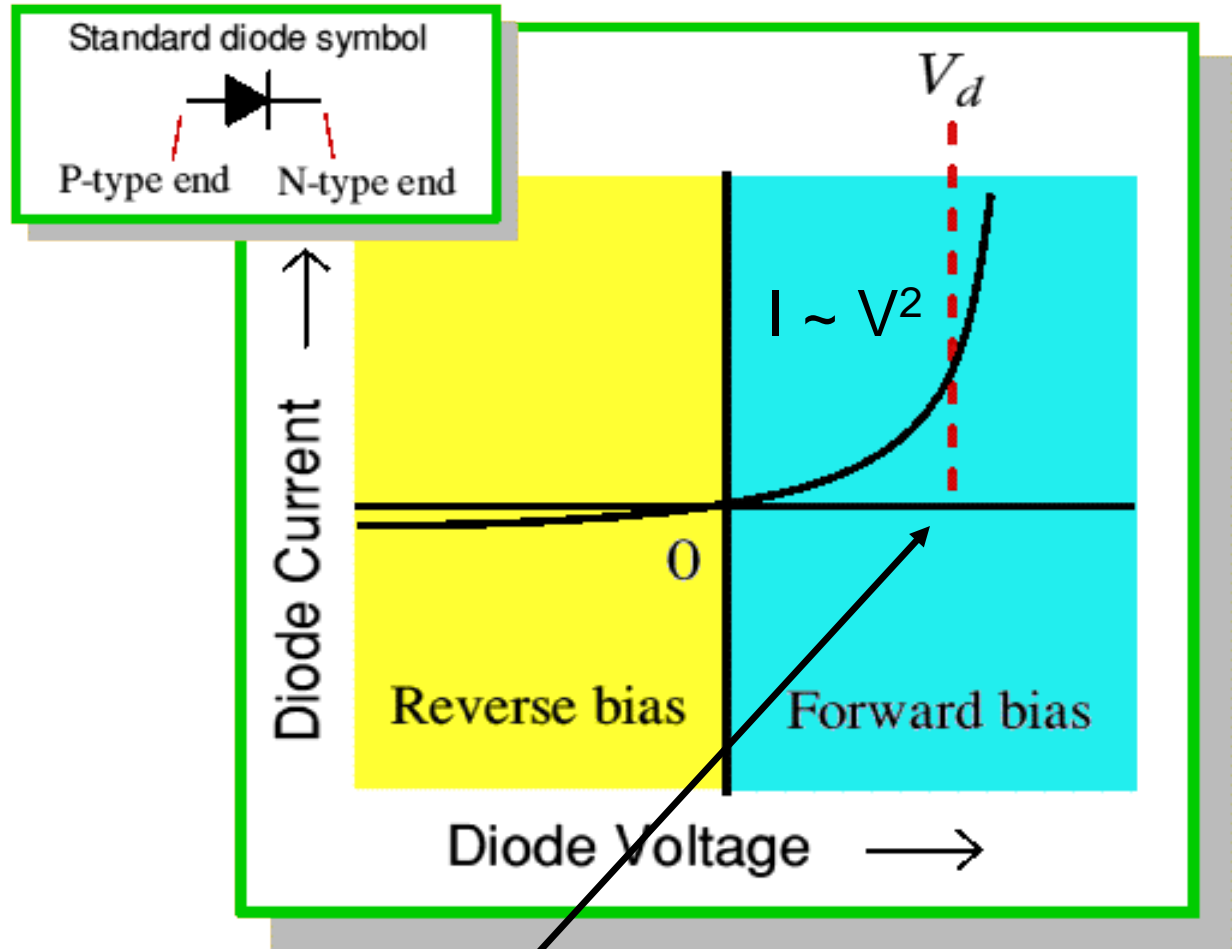
Treat as conductor



Reverse bias

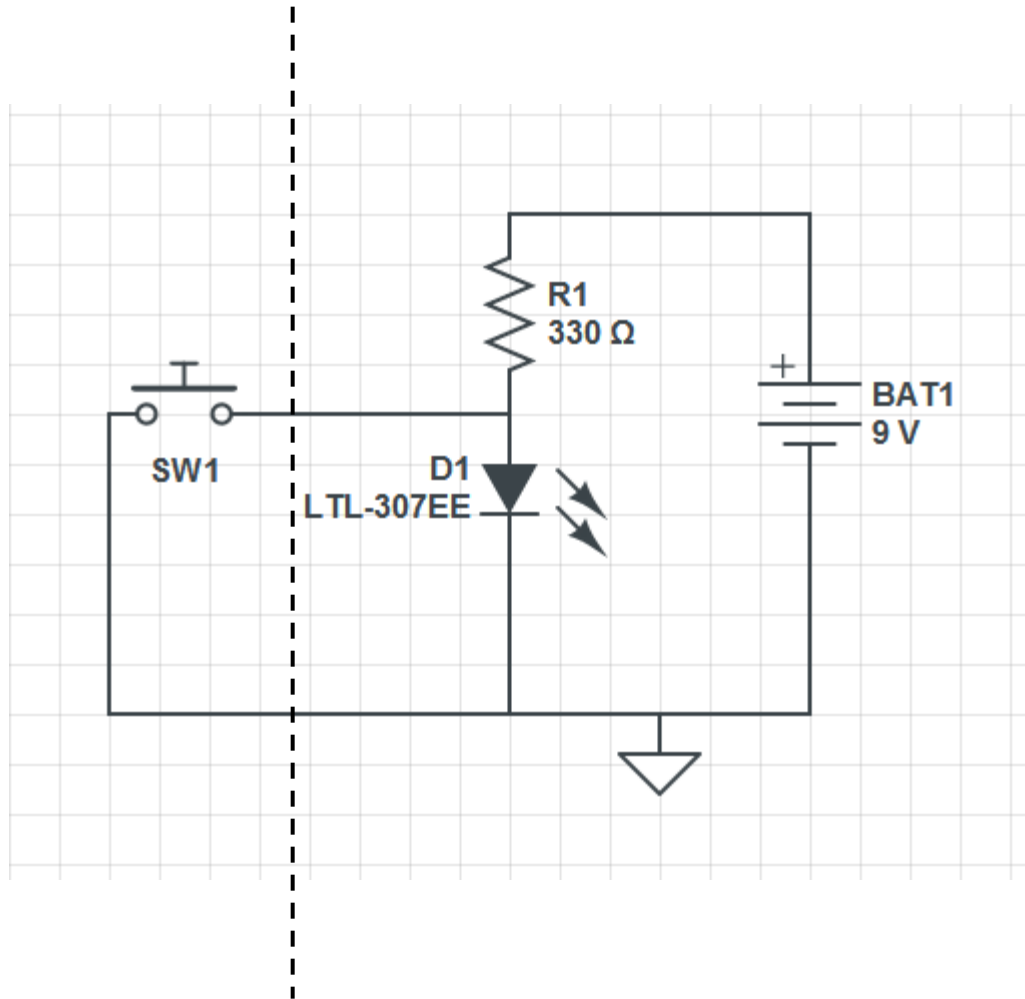
$$I = 0 \text{ A}$$

Treat as open circuit

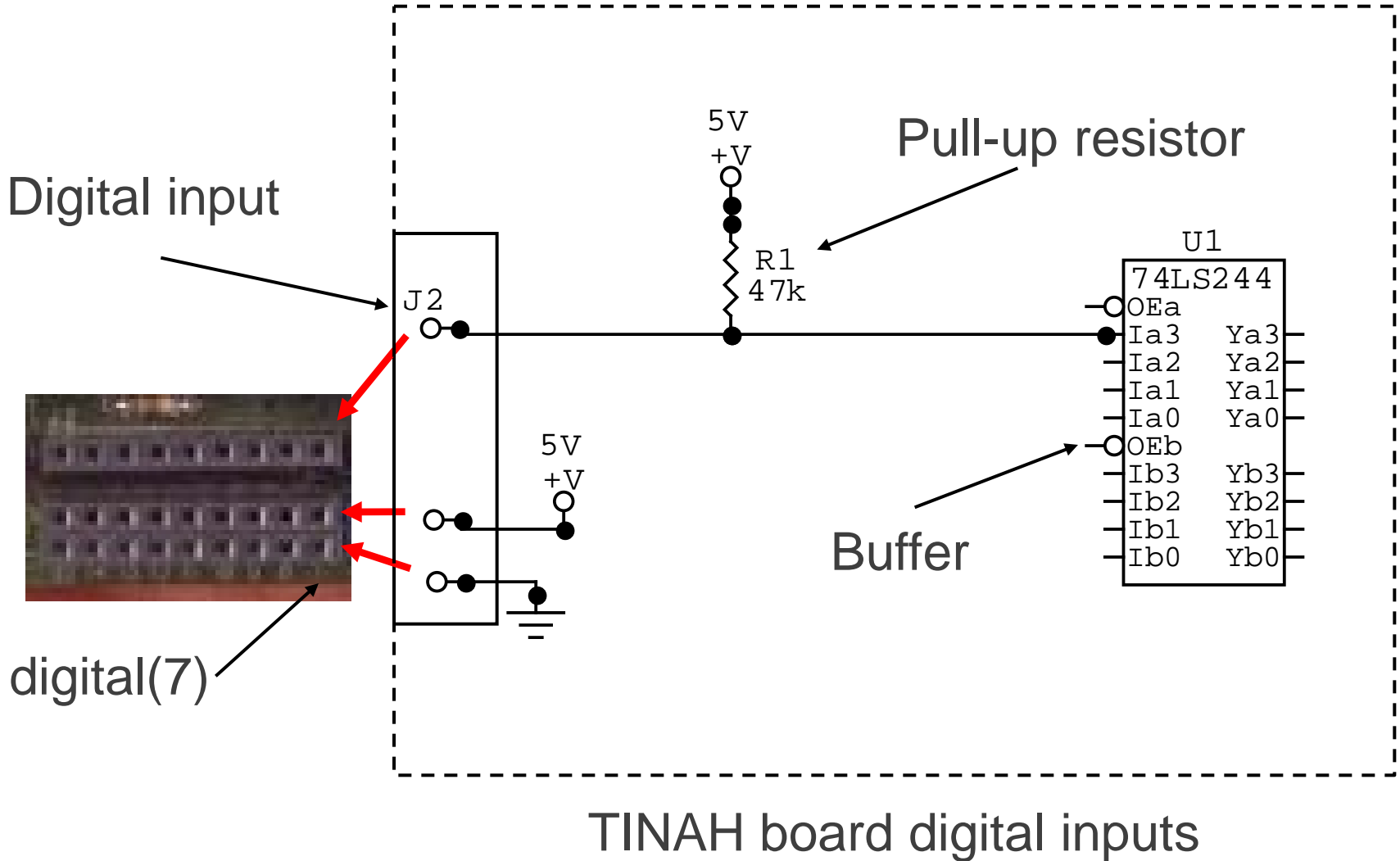


Typical  $\sim 0.7 \text{ V}$

# Digital Inputs – Touch sensor

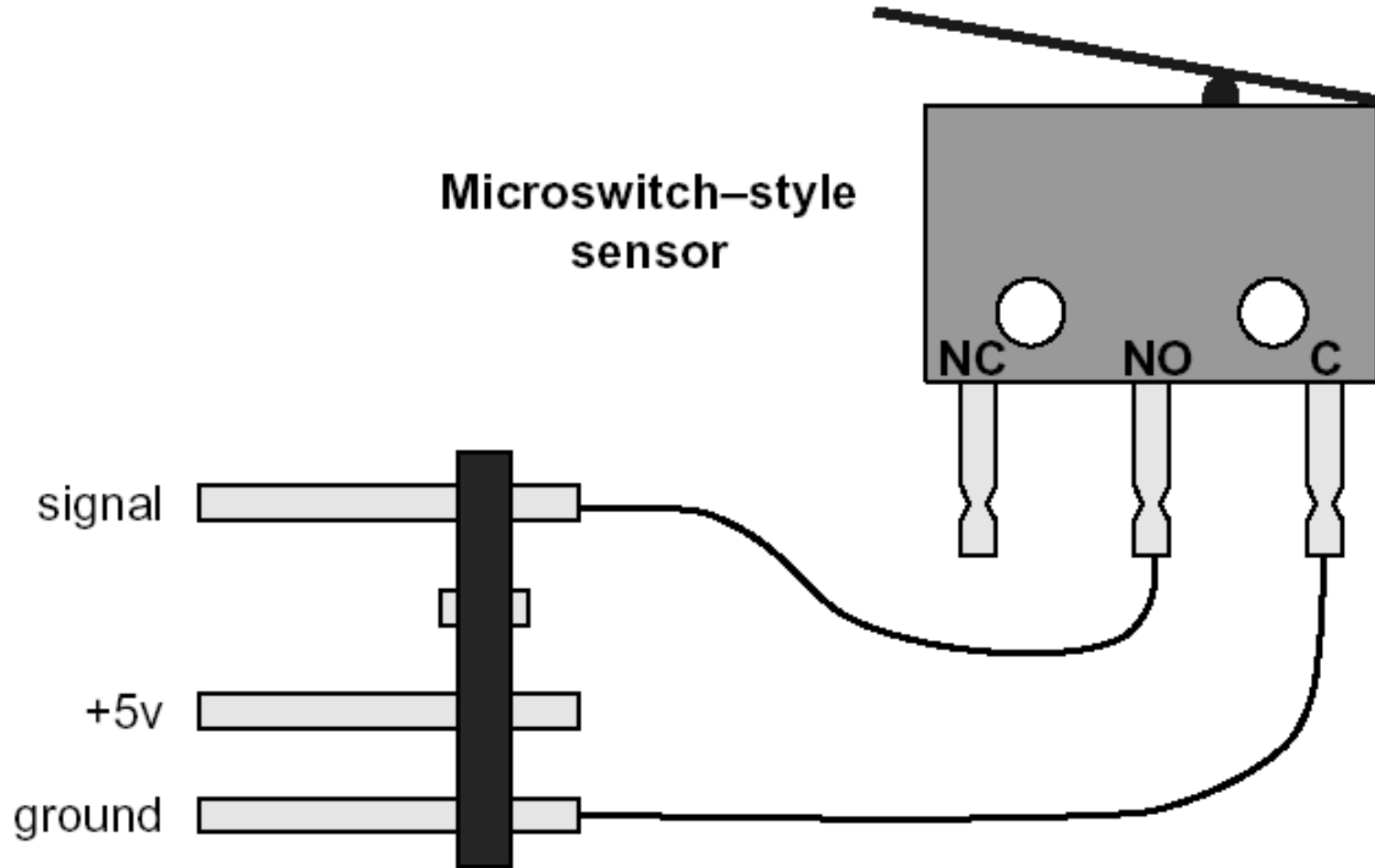


# Digital Inputs – Getting information INTO your microprocessor



# Digital Inputs – Touch sensor

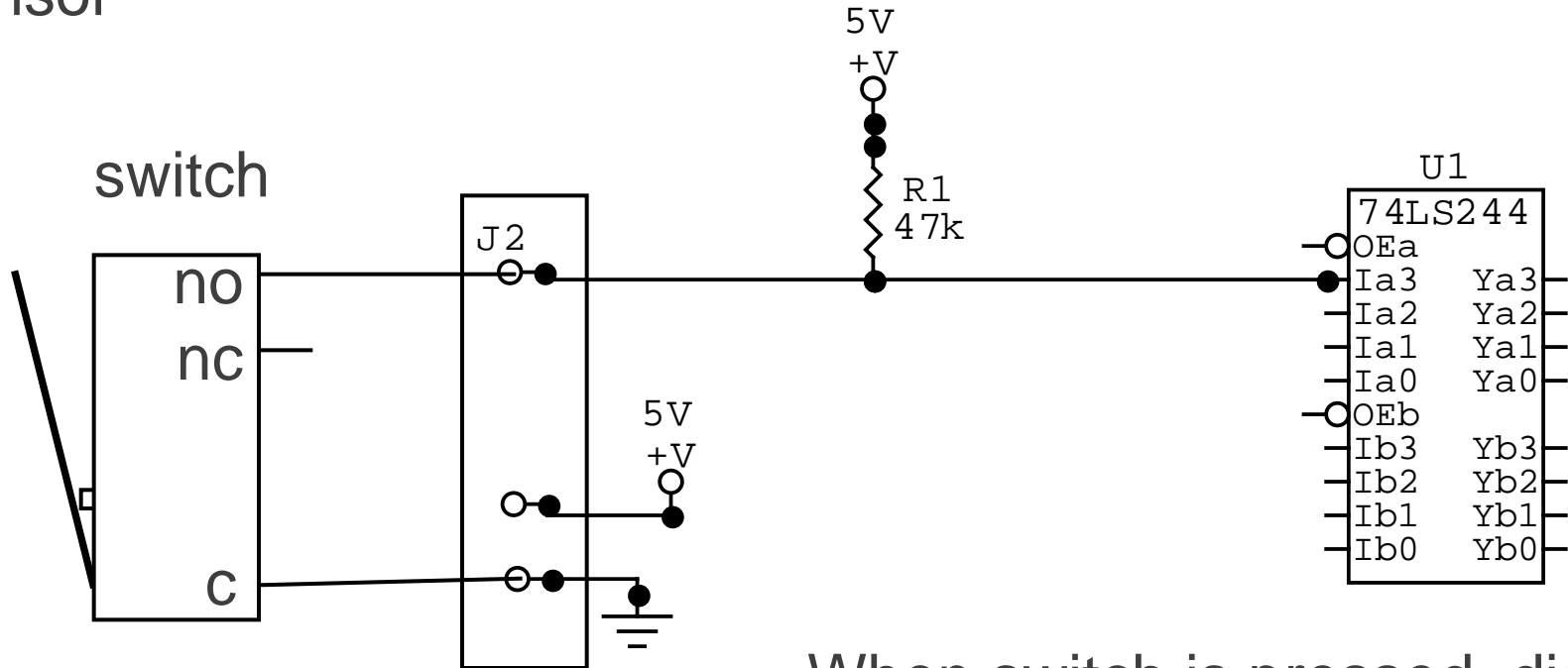
## 6.3.2 Switch Sensor



Wire to switch terminals labelled  
**C** (common) and **NO** (normally open)

# Digital Inputs – Touch sensor

- A simple mechanical switch can be used as a collision or touch sensor



```
if (digitalRead(0))
{ LCD.print("switch NOT pressed"); }
else
{ LCD.print("Collision!!"); }
```

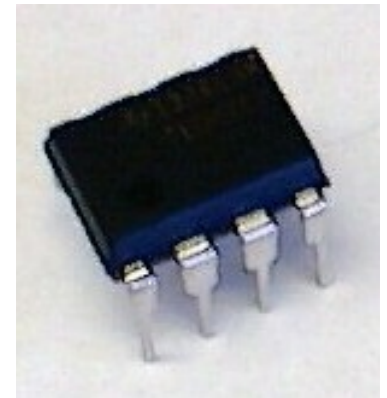
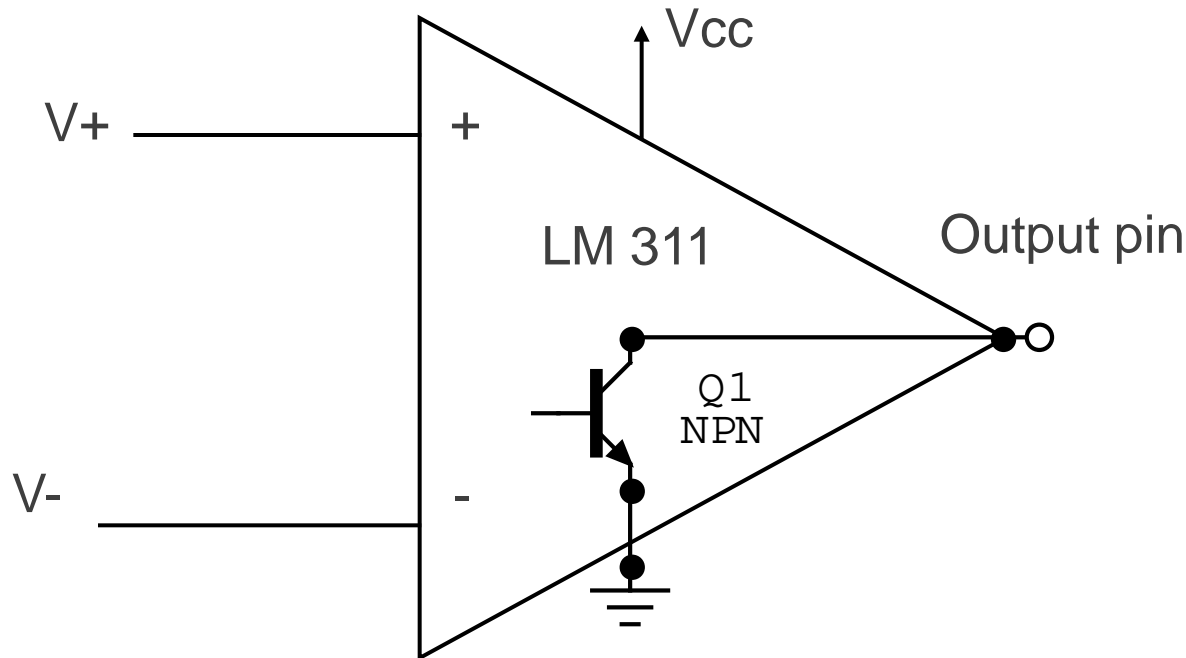
When switch is pressed, digital input is pulled low (0 V) by the switch.

When not pressed it is pulled high (5V) by the resistors

**Step 1b – What if a sensor is not ON/OFF?**

## LM311 comparator – open collector output

- Comparators and other chips are sometimes provided with **Open Collector outputs** for easy interfacing to digital inputs.



When  $V+ < V-$ , Q1 is turned on (conducting). Output pin is grounded through Q1. When  $V+ > V-$ , Q1 is off, and output pin floats unless externally pulled up!!!. (but Q1 cannot sink any current to ground).

Remember: it takes very little charge to change the voltage of a disconnected wire!

# LM311 comparator – Example of a data sheet

## 5.0 Absolute Maximum Ratings for the LM311 (Note 12)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Total Supply Voltage ( $V_{84}$ )	36V
Output to Negative Supply Voltage ( $V_{74}$ )	40V
Ground to Negative Supply Voltage ( $V_{14}$ )	30V
Differential Input Voltage	$\pm 30V$
Input Voltage (Note 13)	$\pm 15V$
Power Dissipation (Note 14)	500 mW
ESD Rating (Note 19)	300V
Output Short Circuit Duration	10 sec

Operating Temperature Range	0° to 70°C
Storage Temperature Range	-65°C to 150°C
Lead Temperature (soldering, 10 sec)	260°C
Voltage at Strobe Pin	$V^+ - 5V$
Soldering Information	
Dual-In-Line Package	
Soldering (10 seconds)	260°C
Small Outline Package	
Vapor Phase (60 seconds)	215°C
Infrared (15 seconds)	220°C
See AN-450 "Surface Mounting Methods and Their Effect on Product Reliability" for other methods of soldering surface mount devices.	

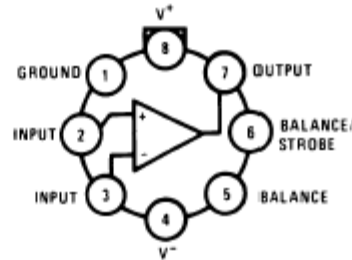
**DANGER LEVELS:** Exceeding these voltages / currents will blow up the chip.



# LM311 comparator – Example of a data sheet

## 11.0 Connection Diagrams

Metal Can Package



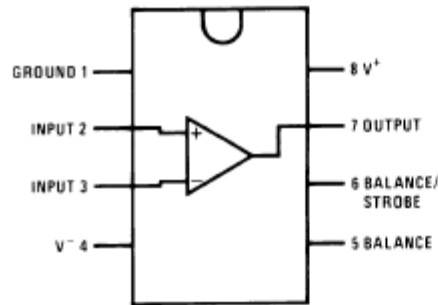
DS005704-6

Note: Pin 4 connected to case

Top View

Order Number LM111H, LM111H/883(Note 21) , LM211H or LM311H  
See NS Package Number H08C

Dual-In-Line Package

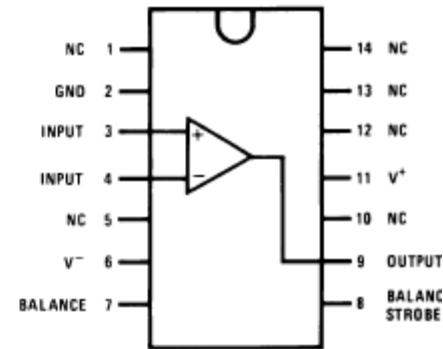


DS005704-34

Top View

Order Number LM111J-8, LM111J-8/883(Note 21),  
LM311M, LM311MX or LM311N

Dual-In-Line Package



DS005704

Top View

The most often used page – how to hook up the chip.

# LM311 comparator – Example of a data sheet

## Electrical Characteristics (Note 15)

for the LM311

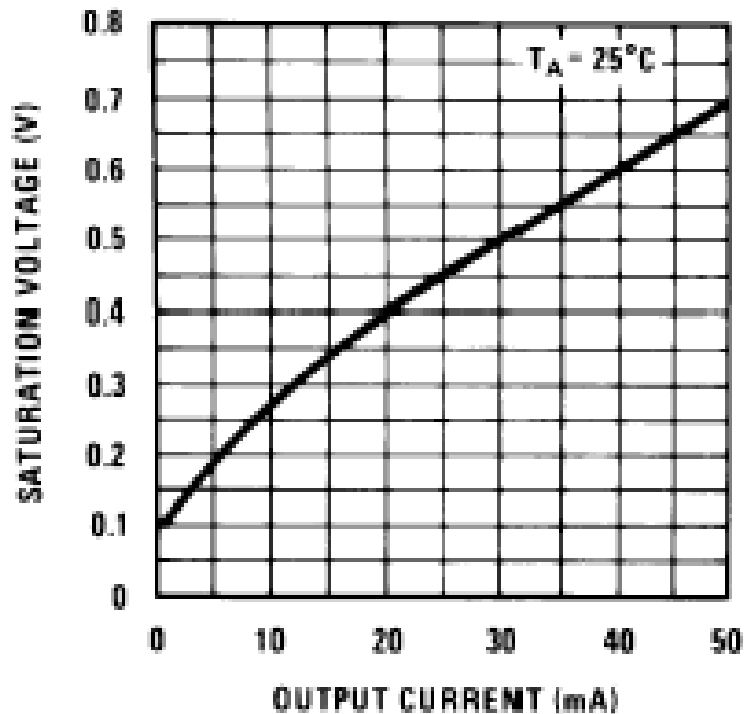
Parameter	Conditions	Min	Typ	Max	Units
Input Offset Voltage (Note 16)	$T_A=25^\circ\text{C}$ , $R_S \leq 50\text{k}$		2.0	7.5	mV
Input Offset Current (Note 16)	$T_A=25^\circ\text{C}$		6.0	50	nA
Input Bias Current	$T_A=25^\circ\text{C}$		100	250	nA
Voltage Gain	$T_A=25^\circ\text{C}$	40	200		V/mV
Response Time (Note 17)	$T_A=25^\circ\text{C}$		200		ns
Saturation Voltage	$V_{IN} \leq -10\text{ mV}$ , $I_{OUT} = 50\text{ mA}$ $T_A=25^\circ\text{C}$		0.75	1.5	V
Strobe ON Current (Note 18)	$T_A=25^\circ\text{C}$		2.0	5.0	mA
Output Leakage Current	$V_{IN} \geq 10\text{ mV}$ , $V_{OUT} = 35\text{V}$ $T_A=25^\circ\text{C}$ , $I_{STROBE} = 3\text{ mA}$ $V^- = \text{Pin } 1 = -5\text{V}$		0.2	50	nA
Input Offset Voltage (Note 16)	$R_S \leq 50\text{K}$			10	mV
Input Offset Current (Note 16)				70	nA
Input Bias Current				300	nA
Input Voltage Range		-14.5	13.8, -14.7	13.0	V
Saturation Voltage	$V^+ \geq 4.5\text{V}$ , $V^- = 0$ $V_{IN} \leq -10\text{ mV}$ , $I_{OUT} \leq 8\text{ mA}$		0.23	0.4	V
Positive Supply Current	$T_A=25^\circ\text{C}$		5.1	7.5	mA
Negative Supply Current	$T_A=25^\circ\text{C}$		4.1	5.0	mA

Important operating characteristics: these numbers will tell you how the chip will behave.

# LM311 comparator – Example of a data sheet

## 7.0 LM311 Typical Performance Characteristics

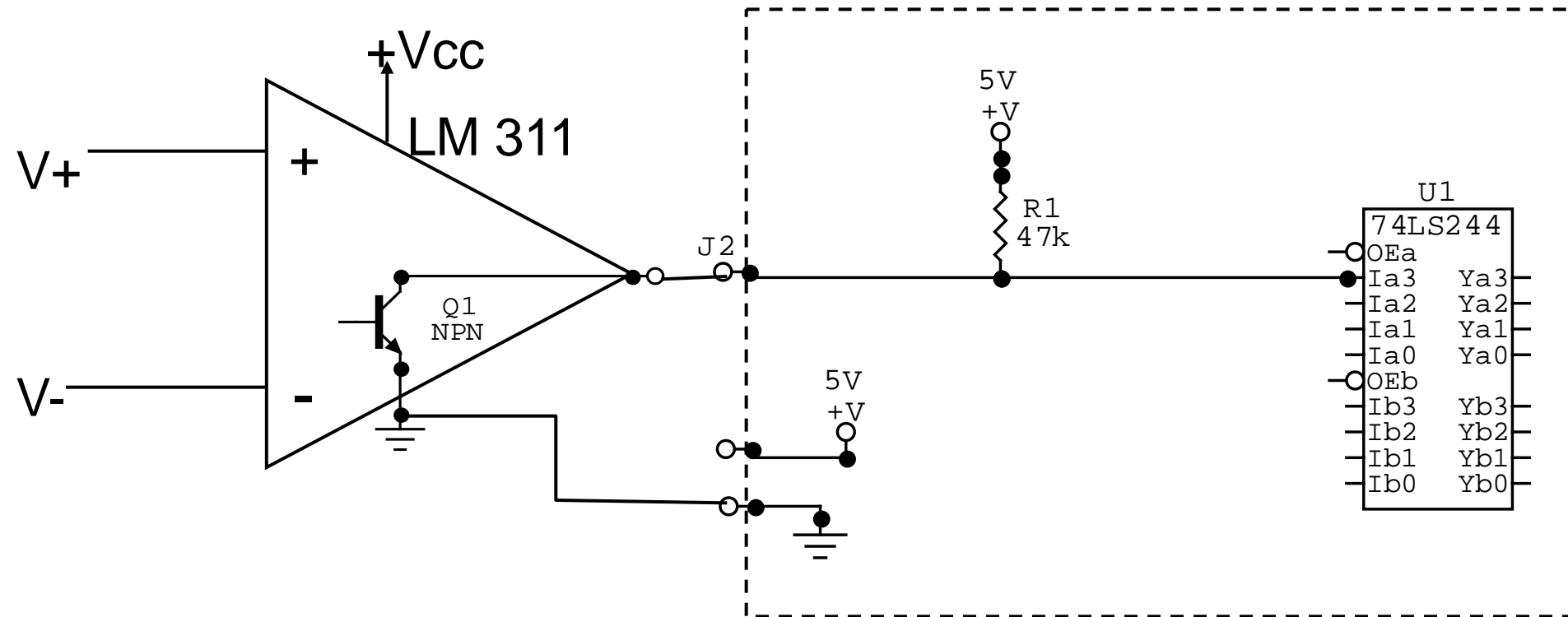
### Output Saturation Voltage



D5005704-66

LM 311 can only sink a limited amount of current

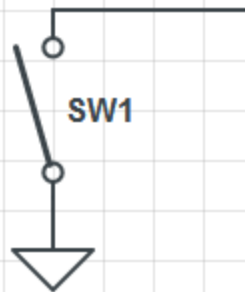
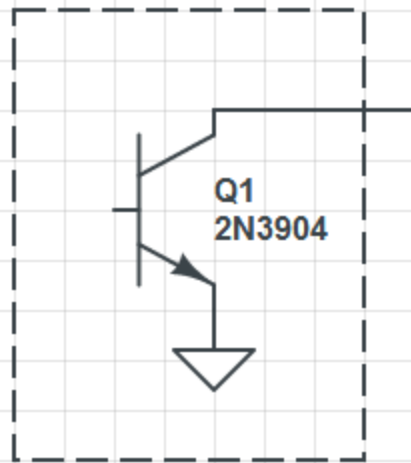
# LM311 comparator – open collector output



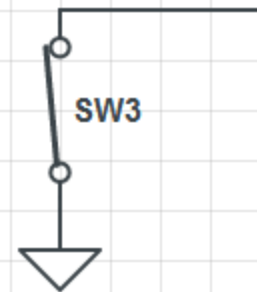
**Unlike an OP-amp, the 311 is NOT a source of power! You cannot drive a load with the output pin.**

Now, when Q1 is off, digital input J2 is pulled high by R1. When Q1 is on, J2 is pulled low ( $\sim 0.1$  or  $0.2$  V) by Q1. Note that the LM311 and the TINAH **must share ground** for this to work, but DO NOT NEED TO SHARE POWER RAILS.

# LM311 comparator – open collector output

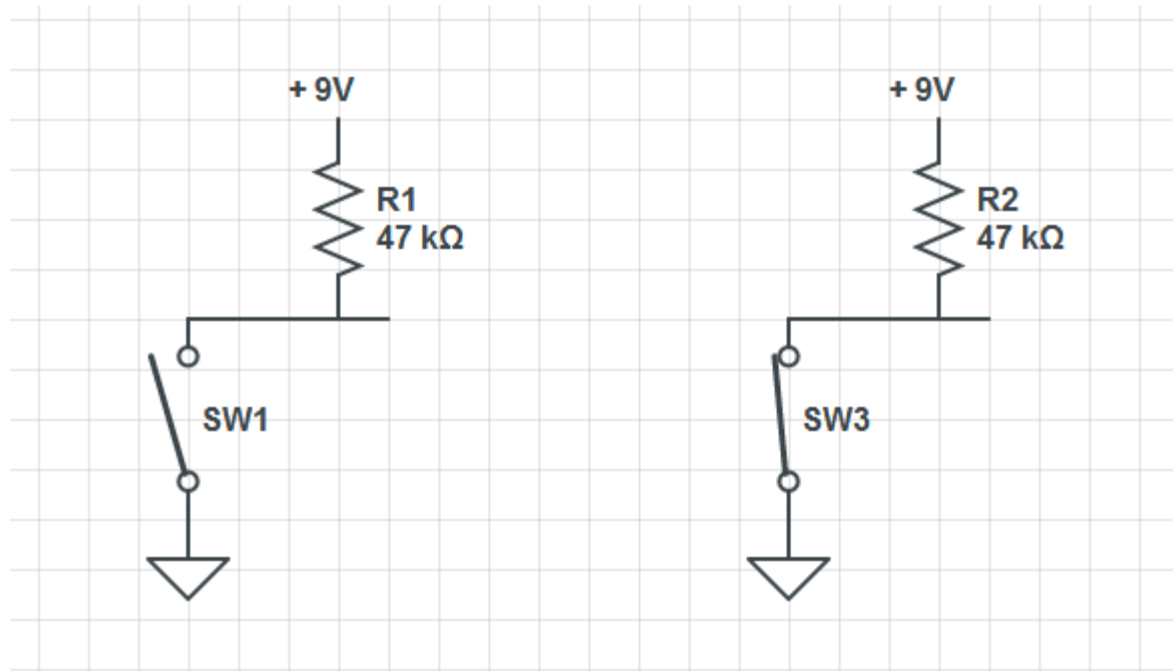


ON



OFF

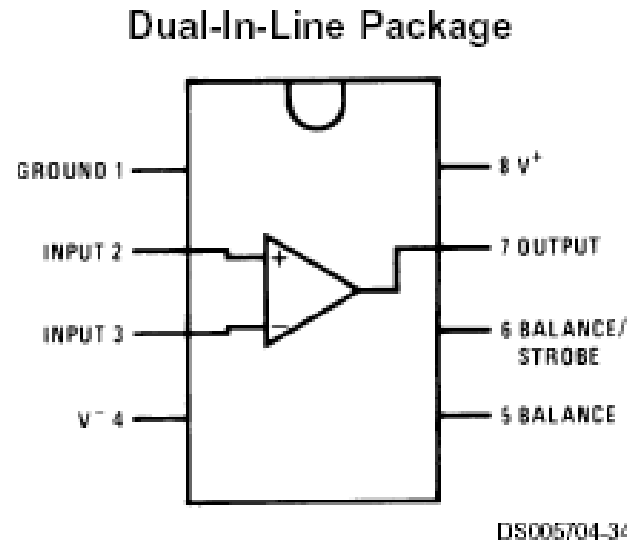
# LM311 comparator – open collector output



ON

OFF

# LM311 comparator – open collector output



Top View

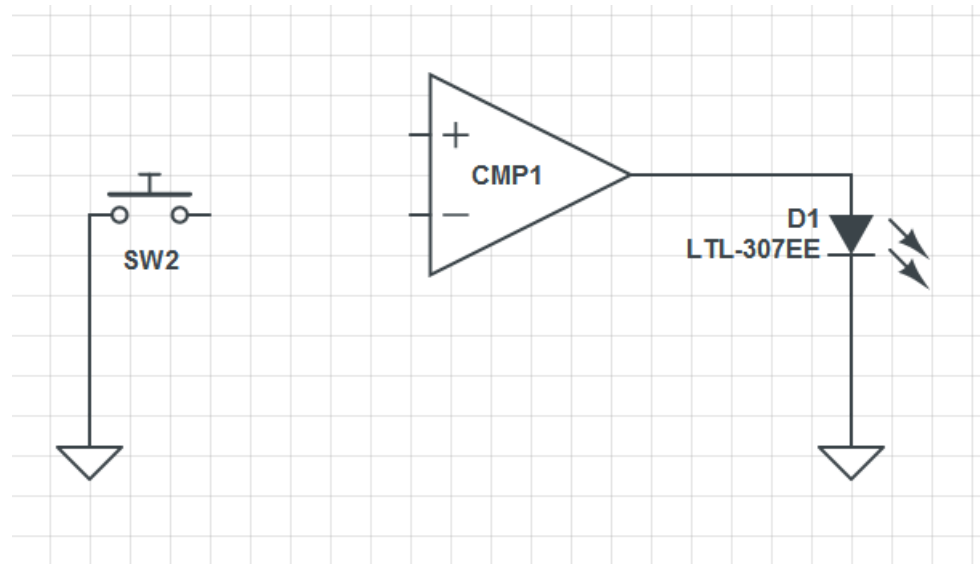
Order Number LM111J-8, LM111J-8/883(Note 21),  
LM311M, LM311MX or LM311N

- You must ground Pin 1 for the comparator to work!
- Pin 7 (Output) must be “pulled up”!

# LM311 comparator – open collector output

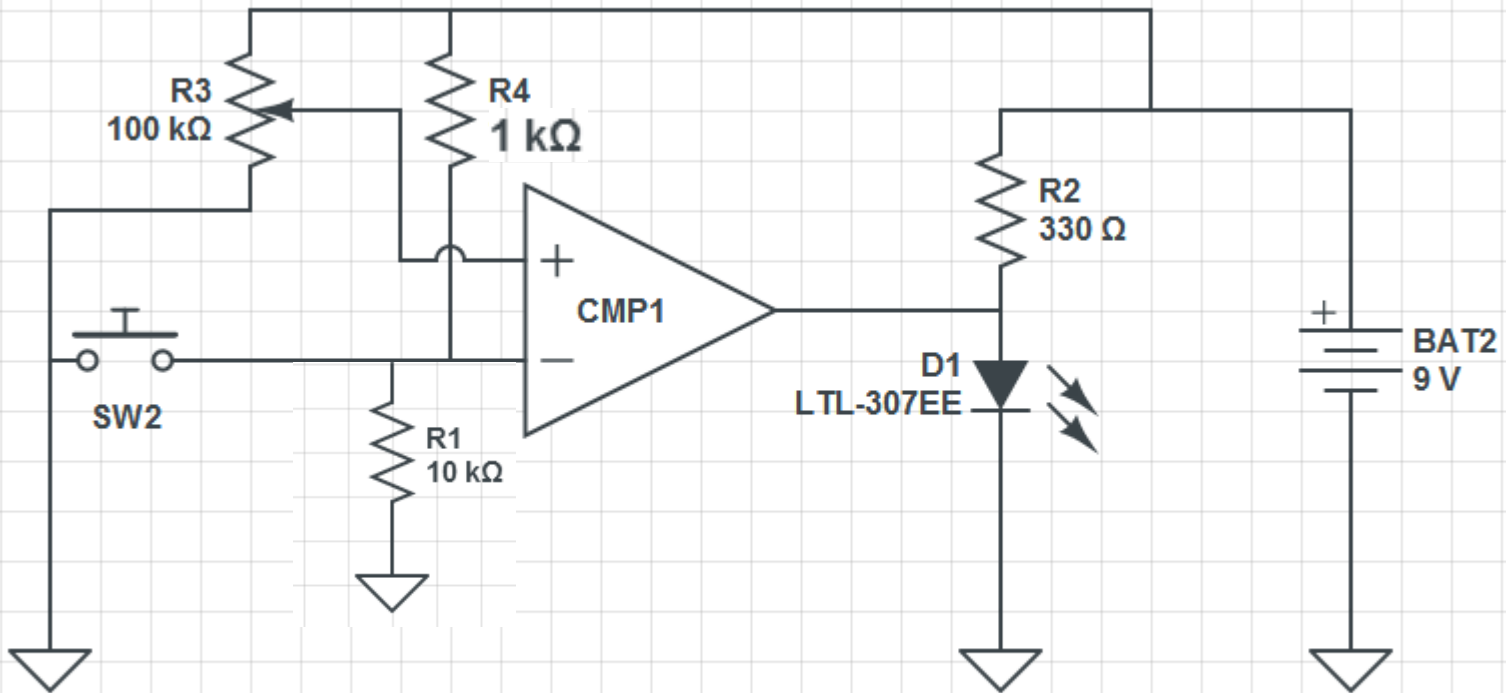
Build a circuit that has:

- An LED that is normally lit
- While a switch is pressed, the LED goes off
- The LED is connected to switch through a 311
- Start with this and add elements:





# LM311 comparator – open collector output

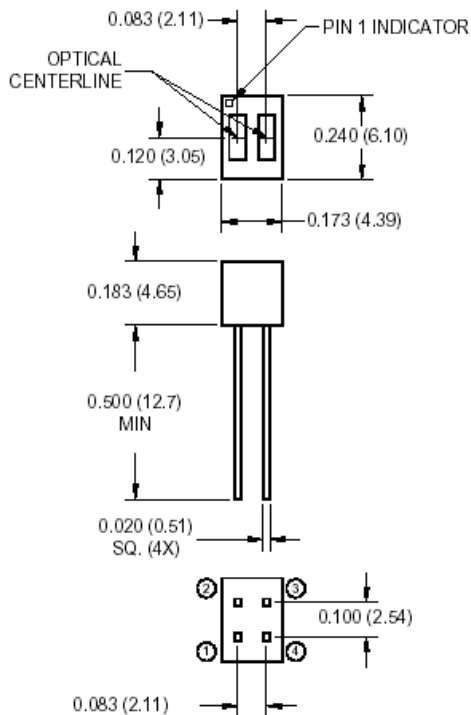


# Example: QRD1114 reflectance sensor



## QRD1113/1114 REFLECTIVE OBJECT SENSOR

### PACKAGE DIMENSIONS



PIN 1 COLLECTOR      PIN 3 ANODE  
PIN 2 EMITTER        PIN 4 CATHODE

#### NOTES:

1. Dimensions for all drawings are in inches (millimeters).
2. Tolerance of  $\pm .010$  (.25) on all non-nominal dimensions unless otherwise specified.
3. Pins 2 and 4 typically .050" shorter than pins 1 and 3.
4. Dimensions controlled at housing surface.

### FEATURES

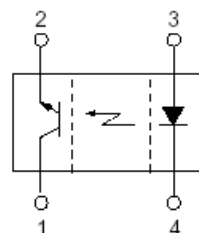
- Phototransistor Output
- No contact surface sensing
- Unfocused for sensing diffused surfaces
- Compact Package
- Daylight filter on sensor



### NOTES (Applies to Max Ratings and Characteristics Tables.)

1. Derate power dissipation linearly 1.33 mW/°C above 25°C.
2. RMA flux is recommended.
3. Methanol or isopropyl alcohols are recommended as cleaning agents.
4. Soldering iron 1/16" (1.6mm) from housing.
5. As long as leads are not under any spring tension.
6. D is the distance from the sensor face to the reflective surface.
7. Cross talk ( $I_{CX}$ ) is the collector current measured with the indicator current on the input diode and with no reflective surface.
8. Measured using an Eastman Kodak neutral white test card with 90% diffused reflecting as a reflective surface.

### SCHEMATIC

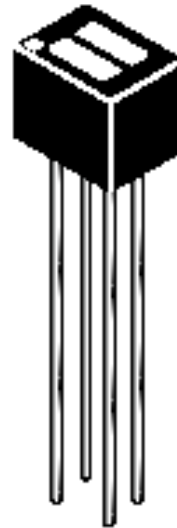


# QRD1114 reflectance sensor

## QRD1113/1114 FIVE OBJECT SENSOR

---

Output  
ice sensing  
ensing diffused surfaces  
ge  
| sensor

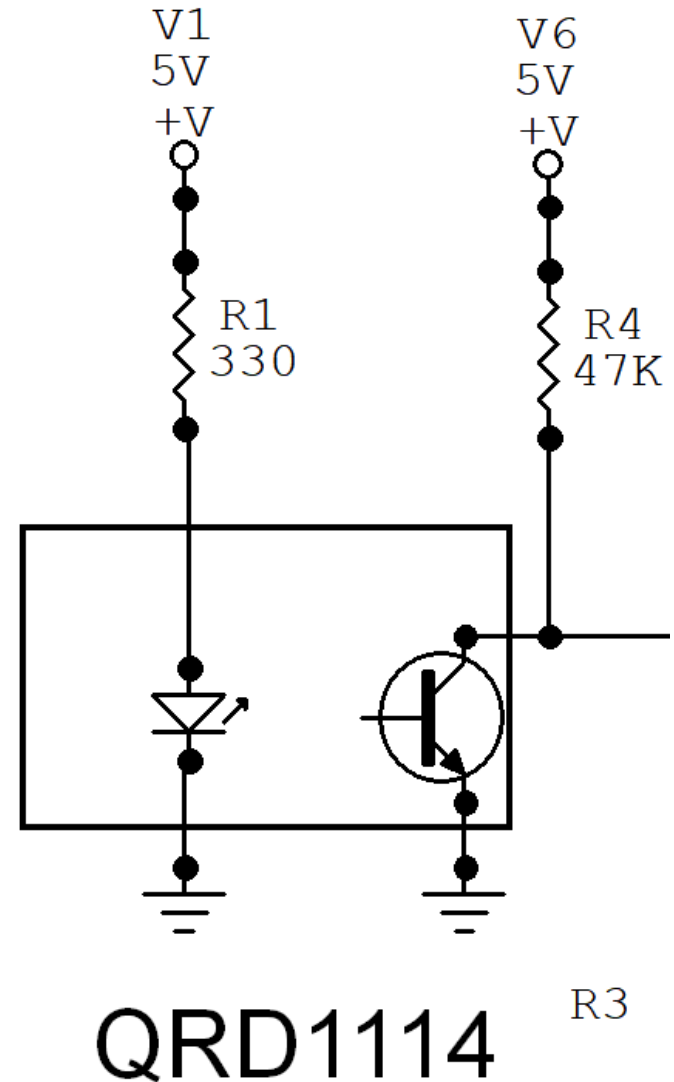


Watch for direct cross-talk: diode and transistor can come out of the housing.

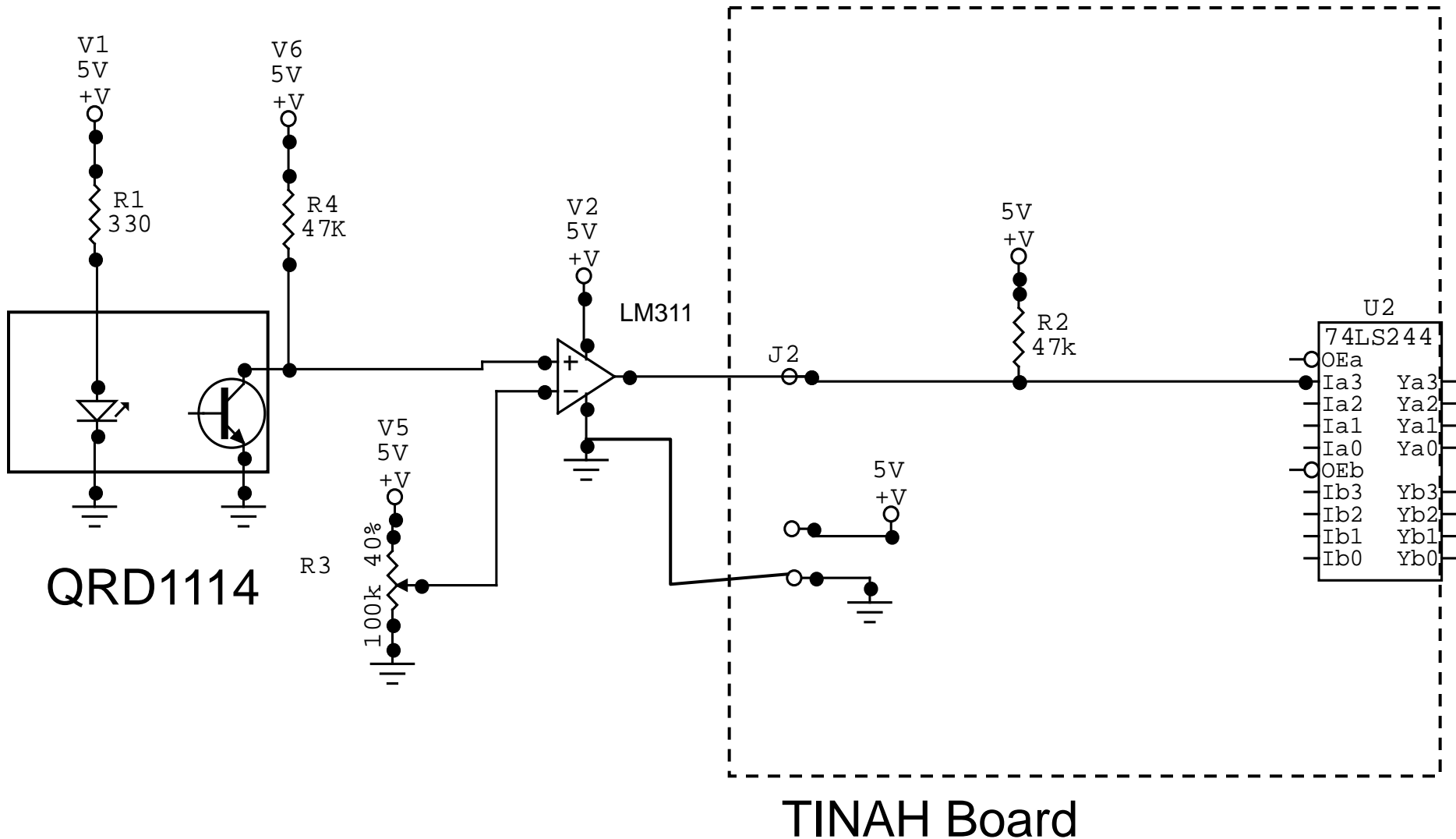
# QRD 1114 – reflectance sensor

Build a circuit to test a QRD sensor:

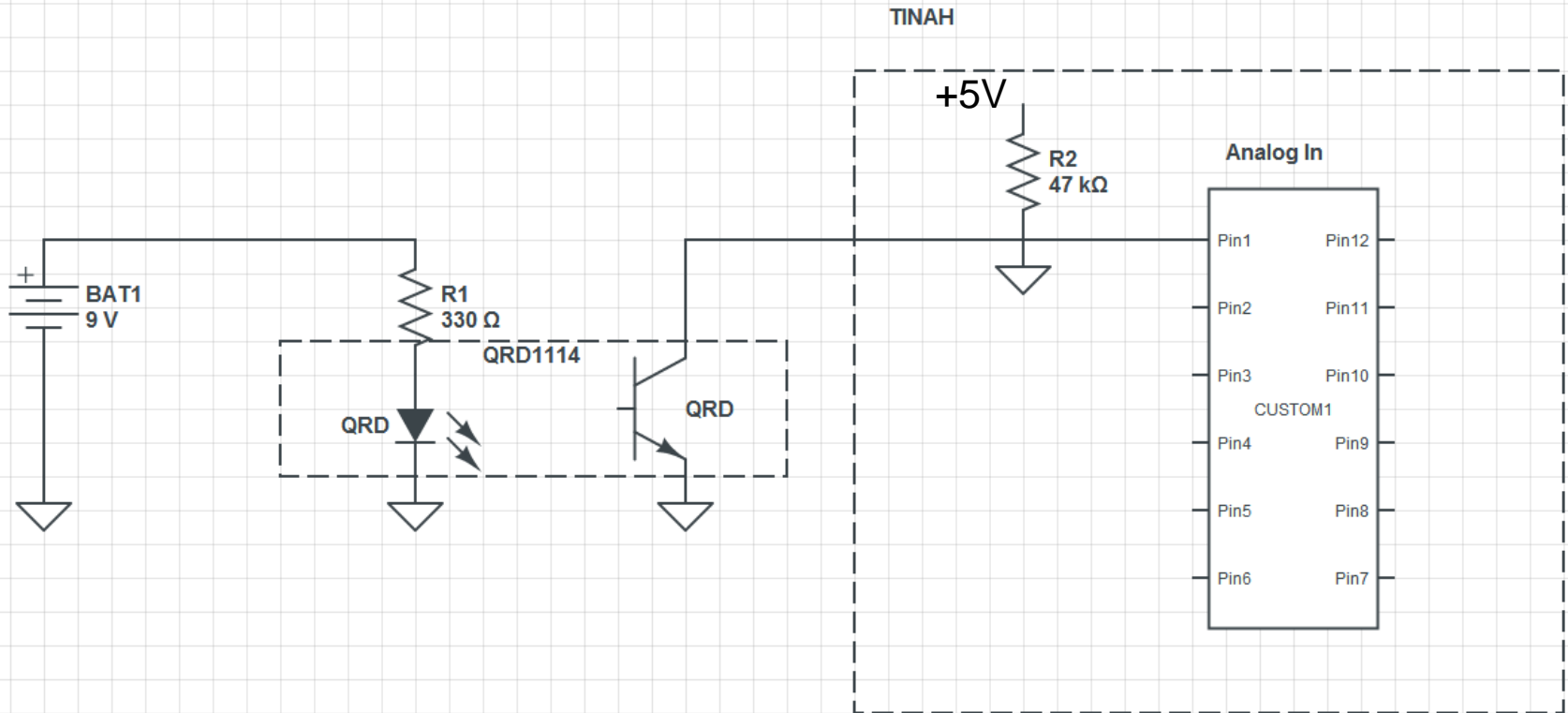
- Use the voltmeter to test that the QRD output responds to light
- See if you or your teammates have a cell phone camera that can see if the QRD is on.
- Add a comparator to this circuit to give you a digital output.



# Example: QRD1114 reflectance sensor



# QRD1114 simple analog connection



# Digital Inputs – QRD sensor - analog

```
while (!startbutton())
{
  LCD.clear(); LCD.home();
  if (analogRead(0)>knob(7))
  {  LCD.print("object NOT detected."); }
  else
  {  LCD.print("object nearby!!");  }
  delay(100) ;
}
}
```

# Things to keep in mind for Lab 1

- Bring a Lab Notebook!

## Common problems:

- Circuit (LM311) and TINAH are not connected to a common ground. **YOU NEED TO CONNECT THEM.**
- The LM311 comparator output pin is not pulled up.
- The power rail break in the proto board is not bridged.
- The strobe pin of the LM311 is pulled low.
- The ground pin of the LM311 is not grounded.
- Blowing up the TINAH. Please use LM311 to interface to the frequency generator.



# Digital Inputs – Touch sensor

```
////////////////////////////////////  
// Physics 253 - Lecture 1  
// 2016  
////////////////////////////////////
```

```
#include <phys253.h>  
#include <LiquidCrystal.h>
```

```
void setup()  
{  
  #include <phys253setup.txt>  
  Serial.begin(9600);  
}
```

```
void loop()  
{  
  while(!startbutton())  
  {  
    LCD.clear(); LCD.home();  
    LCD.print("Welcome to 253!");  
    delay(1000) ;  
    LCD.clear(); LCD.home();  
    LCD.print("Pickup kits");  
    LCD.setCursor(0,1) ; LCD.print("at front of room");  
    delay(1000) ;  
  }  
}
```

```
while (!stopbutton())  
{  
  LCD.clear(); LCD.home();  
  if (digitalRead(0))  
  { LCD.print("switch NOT pressed"); }  
  else  
  { LCD.print("Collision!!"); }  
  delay(100) ;  
}
```

```
while (!startbutton())  
{  
  LCD.clear(); LCD.home();  
  if (analogRead(0)>knob(7))  
  { LCD.print("object NOT detected."); }  
  else  
  { LCD.print("object nearby!!"); }  
  delay(100) ;  
}  
}
```